# Modeling consumers' likelihood to adopt autonomous vehicles based on their peer network

4 Ishant Sharma, Sabyasachee Mishra\*

Department of Civil Engineering, University of Memphis, Memphis, Tennessee, 38152, United
States

### 9 Abstract

10

1 2

3

5

Adoption of connected and autonomous vehicles (CAVs) is viewed as one of the vital factors by 11 12 public and private agencies as benefits are slowly getting quantified with further advancement in 13 technology. From a wide variety of CAV perception and demand estimation studies, the literature 14 lacks the impact of adoption based on an individual's social network and values. In this paper, we 15 utilize an integrated choice and latent variable model to capture individuals' likelihood to adopt 16 level 4 CAVs based on their social values in their peer network using an institutional survey 17 dataset. The model results suggest that households with high income and frequent car buyers are 18 more likely to adopt CAVs. CAV adoption will have a positive influence on an individual's social 19 values among his peers. The proposed framework can be used to provide useful insights for 20 policymakers to quantify consumers' preferences about CAV adoption based on their social values. 21 Keywords: integrated choice and latent variable model, latent attitudes, exploratory factor 22 analysis, ordinal logit, structural equation modeling.

#### 23 1. Introduction

Connected and autonomous vehicles (CAVs) will be an intrinsic part of the daily travel modes,
in terms of personal, public or shared mobility, shortly because of their potential of technologyassisted driving and hence minimizing errors caused by human drivers (Fagnant and Kockelman,
2015; Gurney, 2013). Society of Automotive Engineers (SAE) and National Highway Traffic
Safety Administration (NHTSA) define five levels (0-5) of driving automation, where the lowest

29 being no automation and highest being full automation (Kyriakidis et al., 2015). In addition to 30 safety, CAVs will provide additional benefits in terms of ability to multitask during travel, 31 flexibility in travel (relocating the house to farther and more convenient location), reduced parking 32 and running costs, travel time savings due to the reduction in congestion and accessibility to elder 33 and non-license holder individuals. However, such benefits will also come at the cost of numerous 34 anticipated barriers like accident liabilities, data safety concerns, the addition of new infrastructure 35 and increased emissions because of increase in vehicle miles traveled (Becker and Axhausen, 36 2017; Fagnant and Kockelman, 2015; Gkartzonikas et al., 2019; Gurney, 2013; Milakis et al., 37 2017).

38 In the US, after Nevada in 2011, 21 other states have already passed legislation for autonomous 39 vehicle operation on public roads (NCSL, 2018). Almost every global automaker company is 40 committed to investing in research, development, and manufacturing of CAVs with plans to have 41 its market penetration from 2020 (Walker, 2018). Google's driverless ride-hailing company's 42 (Waymo) driverless cars are already offering services in Arizona, Phoenix (Waymo, 2018). These 43 trends and many others, vindicate the imminent dominance of CAVs in providing mobility in the 44 next decade. However, such commitments from government legislation, automotive 45 manufacturers, and technology-related companies will not be enough for CAV adoption until the 46 CAVs meet the perceptions, demands, beliefs, and needs of end-users at a justified cost. Also, it 47 will be more of a paradigm shift to adopt CAVs from the existing human-driven conventional 48 vehicles in addition to their anticipated barriers and benefits of CAVs.

There are numerous studies available in the literature to document these perceptions and preferences of individuals towards the CAV adoption (Asgari and Jin, 2019; Bansal and Kockelman, 2017; Daziano et al., 2017; Haboucha et al., 2017; Howard and Dai, 2014; Lavieri et

52 al., 2017; Leicht et al., 2018; Liu et al., 2019a; Nazari et al., 2018; Nordhoff et al., 2018; 53 Panagiotopoulos and Dimitrakopoulos, 2018; Shin et al., 2015a; Simpson et al., 2019; Simpson 54 and Mishra, 2020; Spurlock et al., 2019; Talebian and Mishra, 2018). In these studies, choice 55 models in the form of binary logit (Cunningham et al., 2019), multinomial logit models (Bansal 56 and Kockelman, 2017; Howard and Dai, 2014; Malokin et al., 2015), mixed logit models (Daziano 57 et al., 2017; Haboucha et al., 2017; Krueger et al., 2016a), ordered logit models (Menon et al., 58 2015), latent class choice models (El Zarwi et al., 2017), the generalized heterogeneous data model 59 (GHDM) (Lavieri et al., 2017) and hybrid choice model (Krueger et al., 2016b; Nazari et al., 2018) 60 have been extensively used to study the individuals' preferences towards CAV adoption utilizing 61 stated preference survey datasets.

62 Adoption behavior of users in the future is expected to be affected due to the exposure and 63 experience of the CAV technologies through social media, household, or workplace interactions 64 (Bansal and Kockelman, 2017). Adoption research from non-transportation related innovations 65 suggests that social network plays a pivotal role in deciding whether to adopt (Cheung et al., 2014; 66 Venkatesh et al., 2003; Wang et al., 2012). Also, the influence of social interaction on individuals' 67 decisions to adopt an innovation depends on the individual's attitudes (Wang et al., 2008). To best 68 of our knowledge, past efforts to study the likelihood to adopt a CAV, while considering social 69 network and interaction, are limited (Leicht et al., 2018; Liu et al., 2019b; Nordhoff et al., 2018; 70 Panagiotopoulos and Dimitrakopoulos, 2018; Spurlock et al., 2019), especially using discrete 71 choice modeling (DCM). Traditional DCM techniques measure an individual's choice behavior 72 based on alternative attributes and an individual's socioeconomic characteristics using tractable 73 models. Also, it has been well established in the past literature that attitudes and perception play 74 an intrinsic role in choice behavior (McFadden, 1986) but, DCM alone cannot capture the irrational

75 behaviors, effect of perception and attitude on the decision process (Atasoy et al., 2013). Attitudes 76 and perceptions being latent can be efficiently analyzed using integrated choice and latent variable 77 (ICLV) or hybrid choice models. Such models are an extension of DCM to capture attitudes and 78 perceptions while relying on structural equation modeling (SEM) to estimate latent variables (Ben-79 Akiva et al., 2002; Bouscasse, 2018). The ICLV modeling framework is being extensively used to 80 capture the effect of attitudes in choice behavior, especially in travel mode choice (Bouscasse, 81 2018). In the upcoming subsections, we review the past related literature available on the adoption 82 of CAVs.

#### 83 1.1. Literature Review

84 This section includes the methodological framework and significant findings of previous 85 studies related to capturing the intention or likelihood to own/adopt and the impact of social 86 influence on the likelihood to adopt. Several studies are available in the literature to investigate 87 user's likelihood to adopt a CAV or to install autonomous vehicle (AV) technology in the existing 88 vehicles (Acheampong and Cugurullo, 2019; Asgari and Jin, 2019; Bansal and Kockelman, 2017; 89 Berliner et al., 2019; Casley et al., 2013; Daziano et al., 2017; Haboucha et al., 2017; Howard and 90 Dai, 2014; Jiang et al., 2019; Kaur and Rampersad, 2018; Kyriakidis et al., 2015; Lavieri et al., 91 2017; D. Lee et al., 2019; J. Lee et al., 2019; Liljamo et al., 2018; Liu et al., 2019b; Manfreda et 92 al., 2019; Nair et al., 2018; Payre et al., 2014; Pettigrew et al., 2019; Schoettle and Sivak, 2014a, 93 2014b; Shabanpour et al., 2018, 2017; Shin et al., 2015b; Tussyadiah et al., 2017; Wang and Zhao, 94 2019), based on social influence (Leicht et al., 2018; Liu et al., 2019b; Nordhoff et al., 2018; 95 Spurlock et al., 2019) while utilizing structural equation models (Asgari and Jin, 2019; Liu et al., 96 2019a; Payre et al., 2014) and hybrid choice models (Nazari et al., 2018). The major findings of all studies which captured the likelihood to adopt CAVs, along with their data, considered level of
autonomy (level 3 to 5) and methods, are delineated in Table 1.

99 1.1.1. Social influence

Although research on the impact of an individuals' social network on their likelihood to adopt CAV is limited, some studies mentioned in Table 1 have considered this effect through social influence either directly (Leicht et al., 2018; Nordhoff et al., 2018; Panagiotopoulos and Dimitrakopoulos, 2018) or indirectly (Liu et al., 2019b; Spurlock et al., 2019).

104 Leicht et al. (2018) defined social influence based on three survey questions, i.e., people will 105 adopt CAVs because others adopt them too; people will buy CAV as it will look them good in 106 front of their friends; all cars will be CAVs as people tend to imitate the buying behavior of their 107 family and friends. Nordhoff et al. (2018) defined social influence based on two Likert scale survey 108 questions: whether people important to respondents will like it when they use a CAV and whether 109 the respondents would like their friends or family to adopt CAVs before they do. Panagiotopoulos 110 and Dimitrakopoulos (2018) defined social influence based on two survey questions: people, 111 whose opinions are valuable to the respondent, will adopt CAVs; Respondents would feel proud 112 if people in their social network see them adopting a CAV.

Liu et al. (2019b) described social influence as the trust of an individual on an automaker manufacturer, government authorities, and technology-based companies. Spurlock et al. (2019) considered social interaction in the form of a characteristic of a transportation mode where whether an individual can choose to interact with other passengers other than family and close friends.

# 117 **Table 1**

# 118 Major findings from previous studies on individual's likelihood to adopt CAVs

	Data (level of autonomy: L3,		<b></b>
Source	L4, and L5)	Approach/Method	Major findings
		United States	of America
Casley et al.	Survey: 467 American respondents		31% of respondents' decision to adopt CAV was influenced by cost, and 61%
(2013)	(L4 and L5)	Survey data analysis	of respondents would wait at least three years to adopt a CAV.
Howard and	Survey: 107 American respondents	T 1 11	
Dai (2014)	(L4 and L5)	Logit model	42% of respondents were more likely to adopt CAVs.
Demost et al	S		Males with high household income, individuals who travel more, and
Bansal et al.	Survey: 347 American respondents	Ordered probit	individuals living in urban areas were inclined to adopt CAV as soon as they
(2016)	(L4 and L5)		are available.
Daziano et	Survey: 1,260 American respondents	Mixed-mixed logit	Individuals knowing existing automation technologies were inclined to adopt
al. (2017)	(L4 and L5)	model	CAVs.
Bansal and			
Kockelman	Survey: 2,167 American respondents	Simulation-based	Around 40% and 33% of respondents were willing to use CAVs for daily
(2017)	(L4 and L5)	multinomial logit model	trips and their children's school trips, respectively.

Lavieri et al. (2017)	Generalized . Survey: 1,832 American respondents (L4 and L5)					
Shabanpour et al. (2017)	Survey: 1,253 American respondents (L3, L4, and L5)	Random parameter logit model	1			
Tussyadiah et al. (2017)	Survey: 325 American respondents (L4 and L5)	Hierarchical regression analysis				
Nair et al.	Survey: 1,365 American respondents	Rank ordered probit				
(2018) Nazari et al.	(L4 and L5) Survey: 2,726 American respondents	model Hybrid choice model	ľ			
(2018) Shabanpour	(L4 and L5) Survey: 1,253 American respondents	Multinomial logit	]			
Asgari and Jin (2019)	Survey: 1,198 American respondents	Structural equation				
Berliner et al. (2019)	(L3, L4, and L5) Survey: 2,261 American respondents (L3, L,4 and L5)	Ordered logit model				

Young and more educated individuals living in urban areas with a tech-savvy lifestyle would be among the early adopters of CAVs.

Individuals with accident history, high annual mileage, living far away from the workplace, innovators, and favorable policies in terms of dedicated lanes were related positively with the likelihood to adopt CAVs.

Individuals were inclined to use CAV taxi as a tourist than as a resident.

Males, multi-person households, and individuals driving alone to work were more inclined to own CAVs.

Men, young adults, self-employed, primary drivers for the household vehicle, and green travel patterns were positively related to adopting a CAV.

People with disabilities, higher income, and high level of education would be among the early adopters of CAVs.

Only 12% of respondents intended to ride in CAV in the next ten years, and tech-savvy respondents were more likely to adopt CAVs

Men, larger households, paying more for buying a new vehicle, increased knowledge about AV technology, and perceiving CAVs safer than

#### conventional vehicles were associated with an increased likelihood of

#### adopting a CAV.

Individuals willing to interact with other passengers while traveling (social Spurlock et Survey: 1,045 American respondents Linear probability interaction) were reluctant to show interest in adopting autonomous al. (2019) (L3, L,4 and L5) model technology. Countries from the rest of the world Hierarchical regression Payre et al. Survey: 421 French respondents (L4 At least 66% of respondents were inclined to use CAVs. analysis (2014)and L5) Survey: 675 South Korean An individual's decision to adopt CAVs depends primarily on its price, Shin et al. Multinomial probit respondents (L3) followed by automation technology. (2015)Kaur and Survey: 101 Australian respondents Confirmatory factor The positive influence of reliability, performance expectancy, and trust on Rampersad (L4 and L5)likelihood to adopt CAV. analysis (2018)Survey: 241 French respondents (L3, Technology acceptance Consumer innovativeness had a positive impact on social influence and Leicht et al. intention to purchase CAVs. (2018)L4, and L5) model Survey: 2,036 Finnish respondents Men, highly educated individuals, living in densely populated areas, and not Liljamo et Cross-tabulation al. (2018) (L3, L4 and L5) owning a vehicle, had positive attitudes towards CAVs. The social influence had positive impacts on behavioral intention to use Survey: 483 Greek respondents (L,3, Panagiotopo Technology acceptance ulos and L4 and L5) model CAVs.

#### Dimitrakopo

ulos (2018)

Acheampon

g and	Survey: 507 Irish respondents (L4 and	Confirmatory factor	Almost 55% of respondents believed that CAVs would become a standalone
Cugurullo	L5)	analysis	mode of travel in the future.
(2019)			
Jiang et al.	Survey: 576 Japanese respondents		
(2019)	(L3, L4 and L5)	Mixed logit model	At least 47% of respondents were willing to adopt level 3+ CAVs.
J. Lee et al.	Survey: 313 Korean respondents (L3,	Structural equation	Psychological ownership and self-efficacy attitude towards CAVs promote
(2019)	L4, and L5)	model	their adoption.
			Direct and indirect effects of social trust on CAV acceptance: The indirect
Liu et al.	Survey: 441 Chinese respondents	Structural equation	effect of social trust developed through risk and benefits described
(2019b)	(L5)	model	acceptance, whereas the direct effect described willingness to pay and
			behavioral intention.
Manfreda et	Survey: 382 Slovenian millennial	Structural equation	Perceived concerns and benefits towards CAVs were related negatively and
al. (2019)	respondents (L4 and L5)	model	positively, respectively, with their adoption.
Pettigrew et	Survey: 1,314 Australian respondents		First movers were among the first buyers and most knowledgeable about
al. (2019)	(L4 and L5)	Latent profile analysis	CAVs, followed by likely adopters and AV ambivalent.

Wang and	Survey: 1,142 Singaporean		Elderly, females, poor and unemployed are more susceptible to risk, hence
Zhao (2019)	respondents (L4 and L5)	less likely to adopt a CAV.	
		Multiple c	ountries
Schoettle	Survey: 1,533 respondents across the		
and Sivak	US, UK, and Australia (L3, L4 and	Survey data analysis	At least 21%, 18%, and 14% of individuals in the US, UK, and Australia
(2014a)	L5)		were very interested in adopting CAVS.
Schoettle	Survey: 1,722 respondents across		At least 40% 47% and 0% of individuals in China India and Ianan wara
and Sivak	China, India, and Japan (L3, L4 and	Survey data analysis	At least 4070, 4770, and 970 of individuals in China, india, and Japan were
(2014b)	L5)		very interested in adopting CAVs.
Kyriakidis et	Survey: 5,000 respondents across 109		69% of individuals believed that CAVs would reach 50% market share by
al. (2015)	countries (L3, L4 and L5)	Correlation analysis	2050.
Haboucha et al. (2017)	Survey:721 American and Israeli respondents (L4 and L5)	Nested logit kernel model	44% of users were in favor of continuing with their regular cars, while 32% of users opted for personally owned CAVs, and remaining users were in favor of shared CAVs.
Nordhoff et	Survey: 7,775 respondents across 109	Spearman correlation	Social influence among individuals was regarded as a deciding factor for the
al. (2018)	countries (L5)	analysis	acceptance of CAVs.
Lee et al. (2019)	Survey:721 American and Israeli respondents (L4 and L5)	Mixed logit and gradient boosting machine	Trip cost, purchase price, and Pro-AV attitude were the deciding factors for an individual to choose CAV.

121 The summary of the literature suggests that studies are scarce in capturing the impact of 122 individual's social network on their likelihood to adopt a CAV based on DCM framework as Leicht 123 et al. (2018), Panagiotopoulos and Dimitrakopoulos (2018) and Nordhoff et al. (2018) utilized 124 SEM, technology acceptance model, principal component analysis, respectively. Also, other 125 previous studies (Liu et al., 2019b; Spurlock et al., 2019) considered the social influence in terms 126 of social trust on various agencies and social interaction during the commute (whether an 127 individual is willing to have a conversation with a fellow passenger) instead of the influence of 128 individuals' social network. Therefore, the contributions of this study are threefold. First, to 129 identify user's perception towards the adoption of CAVs based on an individuals' attitudes towards 130 anticipated (i) Impact on social values after buying a CAV, (ii) Barriers associated with CAVs, 131 (iii) Benefits associated with CAVs, (iv) Purchase characteristics (price, quality, and environment) 132 associated with CAVs. Second, to test the hypothesis, "owning a CAV will increase an individual's 133 social status just similar to buying a luxury car." *Third*, to capture users' likelihood to adopt a CAV 134 based on their social network interaction. We utilized an ICLV modeling framework based on an 135 institutional survey dataset to test the hypothesis and capture the likelihood to adopt CAVs. The 136 survey dataset included perceptions and attitudes towards level 4 CAVs. As per NHTSA, a level 137 4 CAV has environmental detection and human equivalent driving capabilities under certain 138 circumstances and requires the human driver to take over during an emergency.

The paper consists of five sections. Section 2 presents the description of the dataset used; Section 3 describes the methodology of the ICLV modeling framework; Section 4 presents the model results, and the discussions with previous studies; and finally, Section 5 concludes the paper with key findings, limitations and future scope of the study.

#### 143 **2. Data**

144 The dataset utilized in this study is based on an institutional stated preference survey data sent to 145 2,449 full-time employees (faculties and staff) of The University of Memphis, Tennessee, in 2017 146 (Talebian and Mishra, 2018). The survey consisted of 41 questions subdivided into four different 147 blocks with an approximate completion time of 10 minutes. In the first and second blocks, 148 individuals were asked about their socioeconomic characteristics (both at the individual and 149 household level) and vehicle ownership and purchasing behaviors. In the third block, respondents 150 were asked their social influence characteristics, including questions about their social network in 151 terms of the social ties established in the workplace and frequency of communication with them. 152 Finally, the fourth block included questions about the benefits and barriers associated with CAVs. 153 The online survey was hosted in Qualtrics and distributed through institutional emails, and 154 twenty-five Amazon gift cards worth \$25 were offered as an incentive to randomly chosen 155 respondents. In the survey, participants were given a brief description of CAVs (level 4) just before 156 introducing the fourth block: "A self-driving car is a vehicle that is capable of sensing its 157 environment and navigating without human input. No driver attention is required for safety; i.e., 158 the driver may safely go to sleep or leave the driver's seat. Self-driving is supported under certain 159 circumstances and areas. Outside of these areas or circumstances, the car will be able to safely 160 abort the trip, i.e., park the car, if the driver does not retake control".

During the two-week survey distribution, 327 responses were recorded with a response rate of 13.3%. Since covering each individual through a survey tends to be more costly and difficult, as an alternative, it is possible to expand the collected aggregated data to generate an artificial or synthetic population representing the true population. Therefore, the collected responses were further expanded to an entire institutional population of 2,449 using the synthetic reconstruction

(SR) approach (Auld and Mohammadian, 2010; Guo and Bhat, 2007; Talebian and Mishra, 2018).
The SR approach is based on an Iterative Proportional Updating (IPU) algorithm, which is capable
of matching both person-level and household-level characteristics of interest. Since the survey did
not include any household-level analysis, only person-level synthesis was employed.

170 2.1 Descriptive statistics

171 Descriptive statistics of categorical and continuous attributes or variables with their modeling 172 notation is presented in Table 2 and Table 3, respectively. For categorical variables, original survey 173 responses for each question had different levels than in Table 2 because for modeling purposes, 174 we reclassified these levels to keep either equal percentage of responses in each level or at least 175 25% percentage of responses in each level. This reclassification applies mainly to variables such 176 as age, personal income, household income, and willingness to pay towards a regular car. The 177 dataset includes 53% male participants, 35% aged above 54, 58% white, 26% with income less 178 than \$35,000, 4% physically challenged, 18% willing to pay \$10,000 more than a regular car to 179 buy a CAV, almost 90% owned a smartphone and on an average, five social connections 180 established at the workplace.

181

- 183
- 184
- 185
- 186
- 187

# **Table 2**

# 189 Descriptive statistics of the categorical attributes (N = 2,449)

Attribute (variable name)	Percentage	Attribute (variable name) Per	rcentage
Gender (Gender)		Disability limiting driving ability (Disability)	
Male	53%	Yes	4%
Female	47%	No	96%
Age (Age)		Approximate annual household income (HHI	ncome)
Less than 40	28%	less than \$65,000	36%
40 to 54	38%	\$65,000-\$110,000	38%
more than 54	35%	more than \$110,000	26%
Race (Race)		Frequency of purchasing a car (CarPurchFreq	)
White	58%	Frequently (once every 1 to 5 years)	35%
Black or African American	33%	Moderate (once every 10 years)	44%
Others	9%	Infrequent (once every 15 to 20years)	21%
Employee category (Emptype)		Any plans to buy or sell a car in the next three	e years
		(CarNext3)	
Staff	67%	Yes	50%
Faculty	33%	No	50%
Approximate annual income (Income)		Willingness to pay towards buying a regular of	car
		(WTP_RegularCar)	
less than \$35,000	26%	less than \$15,000	30%
\$35,000-\$65,000	44%	\$15,000-\$30,000	48%
more than \$65,000	30%	more than \$30,000	21%
Frequency of working from home (TeleWork	kfreq)	Flexible work schedule (ScheduleFlex)	
Frequent (daily to once a week)	30%	Yes	56%
Sometimes (once in a month or year)	28%	No	44%

Never	42%				
Willingness to pay more towards buying a CAV	Annual willingness to pay towards maintaining a CAV				
regular car (CAV_Adopt)		than a regular car (WTP_AV_AnnMaint)			
less than \$2,500 (Less)	38%	Nothing or \$0	32%		
\$2,500-\$10,000 (Moderate)	44%	\$0-\$300	34%		
more than \$10,000 (More)	18%	more than \$300	33%		
Frequency of communication with social ties de	veloped	Listens to Radio (Radio)			
at work (CommFreq)					
Frequent (daily to 2-3 times a week)	82%	Yes	97%		
Sometimes (2-3 times a month)	11%	No	3%		
Infrequent (2-3 times a year)	8%				
Own a Smartphone (Smartphone)		Watches TV (TV)			
Yes	90%	Yes	97%		
No	10%	No	3%		

190

191 To the best of our knowledge, we did not find any previous study targeting institutional 192 population; however, we compared our sample (N=2,449) with Nazari et al. (2018) (N=2,726), 193 where authors used Puget Sound regional travel survey program dataset to study the public interest 194 in adopting owned and shared autonomous vehicles and is delineated in Table 4. The proportion 195 of males and females in our sample is almost equal to Nazari et al. (2018). Also, the age statistics 196 are similar to Nazari et al. (2018), with a difference of 7% and 6% in respondents aged between 197 18 to 35 and more than 35, respectively. Both the samples have a similar household income of less 198 than \$50,000 (2% difference) and a difference of 4% and 5% in household income \$100,000 to 199 \$150,000 and more than \$150,000, respectively. However, the number of household members and

200 vehicle ownership was 36% more and 40% less in our sample as compared to the survey sample

- 201 of Nazari et al. (2018).
- 202 **Table 3**
- 203 Descriptive statistics of the continuous attributes (N = 2,449)

Attribute (variable name)	Percentage	Attribute (variable name)	Percentage			
Number of household members (HHSize)		Number of owned cars (household) (HHCars)				
1	23%	0	29%			
2	34%	1	46%			
3	20%	2	19%			
4	14%	3	6%			
5+	8%					
New cars purchased over the last ter	n years	Used cars purchased over the last ten year	ars			
(HHCarsHist10)		(HHCarsHistUsed10)				
0	8%	0	34%			
1	31%	1	24%			
2	33%	2	21%			
3	17%	3	13%			
4+	12%	4+	7%			

Number of close social ties established at work (SocTies)

Mean	4.79
Standard deviation	4.96
Median	4
Minimum	0
Maximum	25

A unique element of the survey was to capture respondent's perception towards the importance of medium of reliable information, input from the social network, impact on personal and social status, barriers, benefits, and attractiveness associated with CAVs, when purchasing a self-driving car, through 23 questions in survey with 7-point Likert response scale (one being very unimportant and seven being very important). Table 5 summarizes the descriptive statistics of indicator variables (Ind01- Ind23) Likert with their notation and description, which we further used in model estimation.

212 Table 5 also includes the percentage of responses for all Likert scale levels of indicator 213 variables. Individuals were not concerned about CAVs being less safe than a regular car. Not 214 surprisingly, individuals were highly concerned about almost all the barriers in terms of CAV 215 breakdown due to system failure, virus attack, and poor internet connection. Individuals were least 216 concerned about losing friends who will not buy CAVs and improvement in social status or 217 personal image after buying a CAV. As expected, respondents were highly concerned about the 218 benefits of CAVs in terms of providing mobility for disabled and generating less pollution as 219 compared to regular cars. Individuals were moderately concerned about the input from their social 220 network when purchasing a CAV. Individuals rated personal research and social ties who already 221 purchased a CAV as the most important factor in deciding on purchasing a CAV. Respondents 222 were highly concerned about the price and quality of CAVs in finalizing their purchasing decision.

223 2.2 Dependent variable (ordered): Likelihood to adopt a CAV

To capture an individual's intention to buy a CAV, we use the question, asking respondent about the reasonable amount they would pay to own/adopt a personal CAV, as the dependent variable, i.e., "*How much MORE would you be willing to pay for a self-driving car than you would*  be willing to pay for a standard car (the one you must operate)?" We then transformed the numerical responses into ordinal with three levels based on the significant percentages in each level and keeping the incipient stage of CAVs and their anticipated initial price: *less likely* (<=\$2,500), equally likely (\$2,500-\$10,000), and more likely (>=\$10,000).

**Table 4** 

Catagorical attributes	Share (%)						
Categorical attributes	This study (N = 2,449)	Nazari et al. (2018) (N = 2,726)					
Gender							
Male	53%	54%					
Female	47%	46%					
Age							
18 to 35	17%	23%					
more than 35	83%	77%					
Household income							
less than \$50,000	25%	27%					
\$50,000-\$75,000	24%	15%					
\$75,000-\$100,000	25%	15%					
\$100,000-\$150,00	14%	19%					
more than \$150,000	11%	15%					
	Ν	Aean (SD)					
Continuous attributes	This study (N = 2,449)	Nazari et al. (2018) (N = 2,72					
Number of household members	2.52 (1.23)	1.85(0.66)					
Number of owned cars (household)	1.01(0.84)	1.67(1.06)					

232 Descriptive statistics: comparison with Nazari et al. (2018)

We used an ordinal dependent variable to complement the results of Cunningham et al. (2019) which included a binary dependent variable representing WTP more against not willing to pay anything and ordinal dependent variables fall under common practice in previous studies (Joewono, 2009; Kim and Vandebona, 1999; Lera-López et al., 2014; Wolinetz et al., 2001). Approximately 18% and 38% of respondents were less and more likely to adopt a CAV, which are marginally close to Cunningham et al. (2019) (23% and 43%).

Since the dependent variable is based on another question in the dataset, represented by variable "Willingness to pay towards buying a regular car (WTP\_RegularCar)," to check the endogeneity between the variables, we performed Durbin-Wu-Hausman (DWH) test (LaFrance, 1993). We used household income (HHIncome) as an instrumental variable based on relevancy and strength test; HHincome was the best representator of WTP\_RegularCar as per significant Ftest results (F-value = 265.33 at p<0). DWH test results indicated that the WTP\_RegularCar is not endogenous to the model as F-test results were not significant (F-value = 0.89 at p=0.35).

246 We considered all explanatory variables for the modeling, including socioeconomic variables, 247 alternative attributes - associated with vehicle purchasing behavior - and social influence variables. 248 In order to avoid multicollinearity, we performed a correlation analysis for all the variables 249 (Spearman for continuous and Cramer's V for categorical), and all the included variables had very 250 little or moderate correlation (Hinkle et al., 2003). We kept both annual income (personal) and 251 annual household income variables in the dataset to capture the likelihood of adopting a CAV at 252 the person and household level as there was no correlation between these variables. We then 253 divided the dataset as **70:30** for model training and cross-validation, respectively.

# **Table 5**

		Likert	Scale l	evels: `	Very U	nimpo	ortant (	(1) to		
Variable name	Likert scale variables		Very Important (7)						Mean	SD.
		1	2	3	4	5	6	7		
Ind01: PersonalImage	Importance to personal image while purchasing a car	17%	27%	12%	18%	19%	4%	2%	3.16	1.60
Ind02: WorkSocialNetImp	Importance of input from work social network when purchasing a self-driving car	6%	8%	10%	16%	29%	24%	6%	4.51	1.58
Ind03: NonWorkSocialNetImp	Importance of input from non-work social network when purchasing a self- driving car	6%	7%	7%	15%	31%	25%	8%	4.65	1.60
Ind04: StatusImprove	Owning a self-driving car will improve individual's status among his peers	37%	33%	9%	17%	2%	1%	2%	2.22	1.35
Ind05: LoseTies	Owning a self-driving car may result in losing friends who won't purchase self- driving car	41%	32%	4%	17%	1%	5%	1%	2.26	1.49
Ind06: PoorInternet	Self-driving feature may fail under poor internet connection	3%	1%	2%	10%	9%	25%	52%	6.02	1.39
Ind07: TakeOver	Driver should take over when CAV fails under poor internet connection	1%	0%	3%	5%	7%	27%	56%	6.22	1.19
Ind08: VirusAttack	Unexpected operations of self-driving car due to virus attack	1%	0%	0%	3%	1%	23%	71%	6.60	0.81
Ind09: SystemFailure	Unexpected operations of self-driving car due to operating system failure	1%	0%	0%	3%	5%	23%	69%	6.56	0.81
Ind10: LessAgility	Lesser maneuverability and agility in auto driving mode of self-driving car as compared to standard car	2%	0%	3%	7%	16%	35%	37%	5.89	1.25

# 255 Descriptive statistics of the Likert attributes (N = 2,449)

Ind11: FullControl	Computer will have full control over car	2%	2%	6%	12%	11%	25%	42%	5.70	1.51
Ind12: AnnMaint	Annual maintenance costs for a self-driving car may be a few hundred dollars more than for regular cars	1%	3%	7%	18%	19%	33%	19%	5.26	1.38
Ind13: LessSafe	A self-driving car might not be as safe as a standard car (the one you must operate)	20%	17%	14%	24%	11%	7%	7%	3.38	1.81
Ind14: TSP	A self-driving car can be synced with traffic lights and other vehicles to decrease travel time	0%	1%	4%	8%	20%	33%	32%	5.75	1.21
Ind15: Green	A self-driving car may generate less pollution compared to a standard car	1%	3%	6%	10%	21%	31%	28%	5.54	1.37
Ind16: MobForDisabled	A self-driving car can provide more mobility for someone with a physical, visual, or other forms of impairment	2%	2%	4%	9%	13%	37%	34%	5.75	1.37
Ind17: FriendRel	Reliable source of information: A friend/co-worker who has already purchased a self-driving car	0%	0%	1%	13%	27%	44%	15%	5.55	1.00
Ind18: Advt	Reliable source of information: Media Advertisements (Print, Television, Radio, Internet)	4%	13%	15%	24%	37%	5%	1%	3.98	1.34
Ind19: Dealer	Reliable source of information: Car dealer	8%	13%	16%	26%	26%	9%	1%	3.80	1.45
Ind20: PersonalResearch	Reliable source of information: Personal research	1%	0%	0%	4%	11%	46%	38%	6.13	0.94
Ind21: CarPrice	Importance of price of car in purchasing decision	5%	0%	0%	1%	8%	32%	54%	6.20	1.35
Ind22: CarQuality	Importance of car quality in purchasing decision	5%	0%	0%	0%	4%	27%	65%	6.38	1.31
Ind23: Environment	Importance of environmental impact in purchasing decision	5%	5%	4%	12%	28%	26%	19%	5.10	1.59

#### 257 **3. Modeling approach**

258 We employed an ICLV modeling framework (Fig. 1) to capture the impact of peer social 259 networks on an individual's likelihood to adopt CAVs. First, we performed an exploratory factor 260 analysis (EFA) to identify attitudinal (latent) variables from the 7-level Likert scale variables 261 (latent indicators in Table 4). Latent variables are then estimated through SEM, with a structural 262 relationship with explanatory variables (Table 2 and Table 3) and a measurement relationship with 263 indicator variables, assuming their error terms as normally distributed (an ordinal probit 264 regression). DCM framework further utilizes the estimated latent variables along with the 265 socioeconomic and household characteristics as explanatory variables with an ordinal dependent 266 variable: likelihood to adopt a CAV (three levels: less likely, equally likely and more likely) 267 (Section 2.2)" while assuming error terms as logistically distributed, i.e., ordinal logit (OL). Then 268 we utilized Monte-Carlo simulation to estimate log-likelihood function, obtained as the probability 269 of OL conditional on the probability of ordinal probit regression of latent variables and maximum 270 likelihood estimator is used to maximize log-likelihood function. A reduced ordinal logit model 271 (without any latent variables) was also estimated to compare the performance of the ICLV model.

#### 272 3.1 Mathematical formulation

Mathematically, two components of ICLV, SEM (Equations 2, 3 and 4) and DCM (Equations 1 and 5) include separate equations for representing structural and measurement relationship between exogenous and endogenous variables respectively (Ben-Akiva et al., 2002):

$$U_n = B \boldsymbol{x}_n + L \boldsymbol{x}_n^* + \boldsymbol{\varepsilon}_n \tag{1}$$

$$\boldsymbol{x}_{\boldsymbol{n}}^* = A\boldsymbol{x}_{\boldsymbol{n}} + \boldsymbol{\gamma}_{\boldsymbol{n}} \tag{2}$$

$$\mathbf{i}_{nr}^* = D\mathbf{x}_n^* + \eta_n \tag{3}$$

$$i_{nr} = \begin{cases} 1 & if \, \mathbf{i}_{nr}^* \le \tau_1 \\ 2 & if \, \tau_1 < \mathbf{i}_{nr}^* \le \tau_2 \\ \dots \\ j \, if \, \mathbf{i}_{nr}^* > \tau_{j-1} \end{cases}$$
(4)

$$y_{n} = \begin{cases} o = 1 & if U_{n} \le \mu_{1} \\ o = 2 & if \mu_{1} < U_{n} \le \mu_{2} \\ \dots \\ o = 0 & if U_{n} > \mu_{o-1} \end{cases}$$
(5)

Equation 1 represents structural equations for the DCM framework where U represents utility for each individual n ( $n \in N$ ) explained by the vector  $\mathbf{x}_n$  ( $K \times 1$ ) consisting of K observable explanatory variables presented in Table 2 and Table 3, vector  $\mathbf{x}_n^*(M \times 1)$  consisting of M unobserved latent variables identified from Likert scale variables in Table 5 and error terms  $\varepsilon_n$ , assumed to be independently and identically distributed (i.i.d.) logistically distributed with  $\Sigma_{\varepsilon}$  as the covariance matrix. *B* and *L* are the matrices with coefficients of explanatory variables ( $1 \times K$ ) and latent variables ( $1 \times M$ ).





Fig. 1. Modeling framework: Integrated choice and latent variable model

Equation 2 represents the structural equation for the SEM framework to calculate the unobserved latent variable  $x_n^*$  described by explanatory variables  $x_n$  ( $K \times 1$ ) with their coefficient matrix A ( $M \times K$ ), reflecting the effect of  $x_n$  over latent variables.  $\gamma_n$  is the vector ( $M \times 1$ ) of error terms assumed to be i.i.d. normally distributed with  $\varphi$  as the covariance matrix. Many terms in  $x_n$  may be zero depending upon their association with latent variables.

290 Equation 3 represents the measurement equation for the SEM framework based on a vector of 291 the random variable  $i_{nr}^{*}$  ( $R \times 1$ ) assumed to be normally distributed and discrete in nature (Likert 292 scale with J levels) for each indicator ( $r \in R$ ) and individual n (Table 4). The indicators are based 293 on the vector of latent variables,  $x_n^*(M \times 1)$ , estimated from equation 2 and matrix  $D(R \times M)$ , 294 capturing the effect of the latent variables on indicators.  $\eta_n$  is the vector  $(R \times 1)$  of error terms assumed to be i.i.d. normally distributed with  $\psi$  as the covariance matrix. Some terms in  $x_n^*$  may 295 296 be zero depending upon the association of latent variables with the indicators. This association is 297 identified using EFA, assuming the cut-off value of 0.4 (Pituch and Stevens, 2015). In Equation 4, 298 the random variable  $i_{nr}^*$  is measured based on the observed vector of indicators and certain thresholds  $\tau_{j-1}$  based on ordinal probit kernel where  $(j \in J)$ . All the error terms  $(\varepsilon_n, \varepsilon_n)$ 299  $\gamma_n$  and  $\eta_n$ ) are assumed to be mutually independent. In this study, survey questions utilized 7-300 301 level Likert scale, as shown in Table 4 (J=7).

Equation 5 represents the measurement equation for the DCM framework, based on ordinal logit kernel, as the dependent variable (Section 2.2), y, is categorical with three ordered categories (*O*) and measured from utility *U*, calculated in Equation 1, and certain thresholds  $\mu_{O-1}$ . 306 ICLV models can be estimated in two steps, i.e., sequentially and simultaneously. In sequential 307 estimation, the SEM framework is estimated first, which enables the flexibility of embedding the 308 estimated latent variables into the DCM framework. Then DCM is estimated traditionally, 309 maximizing the likelihood function conditional on explanatory and latent variables. In 310 simultaneous estimation, both SEM and DCM modeling frameworks are estimated together where 311 the likelihood function is conditional on the explanatory, latent, and indicator variables (estimating 312 all the four equations 1 to 5 jointly) (Walker, 2001). Sequential estimation often results in 313 inconsistent estimates with measurement errors due to the assumption of assuming latent variables 314 as independent of the DCM framework. Simultaneous estimation resolves this limitation but at the 315 expense of increased model complexity and computational effort. Although there is no statistical 316 difference between results obtained from sequential and simultaneous estimations, the 317 simultaneous estimation outperforms sequential estimation in model fitting (likelihood) and policy 318 analysis, such as forecasting (Raveau et al., 2010). The main aim of this study is to identify the 319 individuals' behavior towards CAV adoption based on their social networks; hence, we used 320 simultaneous estimation. The likelihood function for simultaneous estimation is given by equation 321 6:

$$\mathcal{L}(y_n | \boldsymbol{x}_n, \boldsymbol{x}_n^*; B, L, \boldsymbol{\Sigma}_{\varepsilon}, A, \varphi, D, \psi) = \int_{\boldsymbol{x}^*} f_{\boldsymbol{y}}(y_n | \boldsymbol{x}_n, \boldsymbol{x}_n^*; B, L, \boldsymbol{\Sigma}_{\varepsilon}) f_{l^*}(\boldsymbol{i}_{nr}^* | \boldsymbol{x}_n^*; D, \psi) f_{\boldsymbol{x}^*}(\boldsymbol{x}_n^* | \boldsymbol{x}_n; A, \varphi) \mathrm{d} \boldsymbol{x}^*$$
(6)

Where first, second and third terms of integrand represent the density functions for the structural equation of DCM, measurement equation of SEM, and structural equation of latent variable, respectively. The joint probability of all three density functions is integrated over a vector of the latent construct  $x^*$  as the latent variables follow this distribution. The density function  $f_y$  is estimated as an ordinal logit kernel based on Equation 5. The integral is evaluated using the Monte Carlo simulation method, with 150 Halton draws from the normal distribution of latent variables  $x_n^*$ , and then the resulting likelihood is estimated using maximum simulated likelihood (MSL).

329 The main idea behind estimating an ICLV over traditional DCM is to improve the 330 prediction of choice behavior (Vij and Walker, 2016) and goodness of fit measures vindicate any 331 models' superiority when compared to other or reference cases in terms of fitting and prediction. 332 ICLV models are becoming a preferred alternative to traditional DCM frameworks as they tend to 333 fit and predict data better. Vij and Walker, (2016) compared ICLV models with the reference case 334 DCM using simulations under different cases based on hypothetical datasets to vindicate the 335 usability of former over latter. The authors conclude that ICLV models should only be preferred 336 over the traditional DCM if they provide additional insights to the decision-making process, 337 different interpretations of the estimates, and better model fit and prediction.

338 ICLV models are usually compared with their reduced form DCM frameworks, either 339 including or excluding measurement indicators depending upon the objectives of the analysis. If the study objectives are to predict choice behavior under hypothetical conditions and indicator 340 341 variables are expected to be absent in future analysis, it is a common practice to exclude 342 measurement indicators from modeling framework to check its goodness of fit against the 343 reference model (Ben-Akiva et al., 2002; Daziano and Bolduc, 2013; Yáñez et al., 2010), i.e., 344 excluding density function of measurement equation of SEM in equation 6 and estimating DCM 345 coefficient matrices B and L. Since the objectives of this study are to predict an individual's 346 behavior towards adopting a CAV through the ICLV framework, we utilized the modeling 347 approach proposed by Vij and Walker (2016) to check the goodness of fit of the estimated model 348 against the reduced choice model. The reduced choice model is only the DCM part of ICLV, i.e.,

an ordinal logit without latent variables. Hence, removing latent variables  $x_n^*$  from equation 1 will form the utility equation for the reduced choice model:

$$U_n = \mathbf{E} \mathbf{x}_n + \epsilon_n \tag{7}$$

Equation 7 represents the structural equation for the reduced choice model framework where U represents utility for each individual  $n \ (n \in N)$  explained by the vector  $\mathbf{x}_n \ (K \times 1)$  consisting of K observable explanatory variables presented in Table 2 and Table 3 with E as the matrix of unknown coefficients. Error term  $\epsilon_n$ , was assumed to be i.i.d. and logistically distributed with  $\Sigma_{\epsilon}$ as the covariance matrix. The reduced choice model was estimated using equation 5 and maximum likelihood estimation for an ordinal logit framework. The goodness of fit measures of ICLV was compared with this reduced choice model to vindicate the superiority of the former.

#### 358 **4. Results**

This section comprises the estimation results for the ICLV model in its two different components; SEM: measurement and structural equation models and DCM: ordinal logit with latent variables, along with the policy implications. A python-based software package, "PandasBiogeme" (Bierlaire, 2018), is used to estimate ICLV, where we first estimated the model sequentially and then used then simultaneously. The model was formulated using 70% of the dataset (N = 1,714), and the remaining dataset (N=735) was used for testing the model and keeping overfitting in check.

#### 365 4.1 Exploratory factor analysis

We performed an EFA to identify the unobserved latent variables from the 23 indicator variables and yielded four factors. We used an R package "psych" (Revelle and Revelle, 2015) and Mplus to model EFA. First, we performed Bartlett's test of sphericity (Bartlett, 1950) and the Kaiser-Meyer-Olkin (KMO) test (Cerny and Kaiser, 1977) to check the sampling adequacy or 370 factorability. We obtained significant results for Bartlett's test of sphericity (Chi-square value = 371 16,803.36 at p = 0.0) and KMO test (0.7037, which is more than the minimum threshold 0.6). To 372 identify the number of factors, we performed scree plot analysis, based on eigenvalues, and based 373 on the scree-plot (Fig. 2), we could choose seven factors as their eigenvalues were greater than 374 one. We used varimax orthogonal rotation and maximum likelihood method for the EFA model 375 after varying the number of factors from 1 to 7. Only four factors had a meaningful interpretation 376 of relationships based upon the nature of questions asked and explained 41% of the cumulative 377 variance in the sample. The model fit indices for four factors were: chi-squared statistic = 1226.86 378 (41 degrees of freedom at p-value = 0), root mean square residual (SRMR) = 0.05, root mean square 379 error of approximation (RMSEA) = 0.13 (90% CI = (0.124, 0.136)) and comparative fit index (CFI) 380 =0.887. The model is sufficient based on chi-squared statistic, SRMR (  $\leq 0.08$  as per Hu and 381 Bentler (1999)), CFI (close to 0.90 as per Bentler (1990)). However, RMSEA =0.132 (<= 0.06 as 382 per for good model fit as per Hu and Bentler (1999) and  $\leq 0.10$  for marginal fit as per Fabrigar 383 et al. (1999)) and reflects a mediocre model fit (Fabrigar et al., 1999). However, Chen et al. (2008) 384 evaluated the use of fixed universal cut off points for RMSEA empirically. They concluded that 385 since population RMSEA is unknown to researchers, RMSEA should not be pursued as a single 386 measure of fit based on the fixed cut-off, and there is a need for other goodness of fit measures. 387 Also, the model shows an acceptable fit when CFI is greater than 0.90, while SRMR is less than 388 0.10 (Kline, 2015). Hence, Bartlett, KMO, chi-squared statistics, CFI (marginally close), and 389 SRMR confirm the validity of the model.

We assume 0.4-factor loading as cut off values (Pituch and Stevens, 2015) for shortlisting the
indicator variables based on their respective factors (bold values in Table 6). Based on the cut-off-

392 values and explicit nature of indicator variables, identified four factors are named as Social Image



393 (SI), CAV Barriers (CBa), CAV Benefits (CBe), and CAV Purchase (CP).







396 The latent variable SI confirms an individuals' perception towards the impact of CAVs on their 397 respective social status among peers and the importance of communication or input from their peer 398 social network. For latent construct SI, among total five indicators; two indicators related to 399 reliable information from advertisements (Ind18) and car dealers (Ind19) are excluded because of 400 their irrelevance with an individual's social network as the importance of information obtained 401 from advertisements and dealers is against the importance of status, work and non-work social 402 network. The latent variable CBa contends an individual's perception towards anticipated barriers 403 associated with CAVs such as the impact on CAV operation under poor internet connection, virus 404 attack or system failure, computer's control over driving the car, and less maneuverability as 405 compared to a standard car. Similarly, the latent variable CBe indicates the attitude towards the 406 anticipated benefits of CAVs in terms of less pollution and providing mobility to disabled persons. 407 Some of the previous studies (Lavieri et al., 2017; Nazari et al., 2018) incorporated the green 408 lifestyle in terms of the importance of living in a walkable neighborhood, close to transit, and close

409 to the workplace (30-minute commute). Hence, we include Ind15 (CAVs less polluting than 410 standard cars) to latent variable Cbe. The latent variable CP reveals the psychological constructs 411 associated with the importance of price, quality, and environmental impact of CAVs in purchasing 412 decisions. Also, the indicator variable Environment (Ind23) is related to two latent variables (CP 413 and CBe). Since the associated survey question reflects impact on car purchasing decision, well 414 supported by high loading in CP as compared to CBe, and is entirely different from green lifestyle 415 as per previous studies (Lavieri et al., 2017; Nazari et al., 2018), we considered Ind23 in latent 416 variable CP.

The estimation approach for the ICLV model, consisting of SEM and DCM, along with the structural and measurement relationships between observed explanatory variables, identified latent variables with their indicators and outcome variable along with their coefficient and random disturbance term matrices is portrayed in Fig. 3.

# **Table 6**

Indicator variable	CAV Barriers	CAV Purchase	Social Image	CAV Benefits
Ind01: PersonalImage			0.343	-0.116
Ind02: WorkSocialNetImp			0.421	0.117
Ind03: NonWorkSocialNetImp			0.479	0.101
Ind04: StatusImprove			0.469	
Ind05: LoseTies			0.313	
Ind06: PoorInternet	0.567	0.217		0.179
Ind07: TakeOver	0.573	0.266		0.172
Ind08: VirusAttack	0.865			
Ind09: SystemFailure	0.853			
Ind10: LessAgility	0.611			0.132
Ind11: FullControl	0.452			
Ind12: AnnMaint	0.299	0.109		0.214
Ind13: LessSafe	-0.335			0.101
Ind14: TSP	0.235		0.245	0.368
Ind15: Green				0.913
Ind16: MobForDisabled	0.245			0.465
Ind17: FriendRel			0.221	0.149
Ind18: Advt		-0.115	0.775	0.266
Ind19: Dealer	0.107	-0.16	0.713	0.198
Ind20: PersonalResearch	0.103	0.11	0.324	
Ind21: CarPrice	0.119	0.826		-0.119
Ind22: CarQuality	0.165	0.917		
Ind23: Environment		0.696		0.508

# 423 Exploratory factor analysis results: latent variables (N = 1,714)

Hypothesis test: 4 factors are sufficient: chi-square statistic: 7,327.87 on 167 degrees of freedom at p-value : 0.

\*Bold estimates: factor loadings greater than the cut-off value of 0.4

#### 424 *4.2 Estimated SEM/latent variable model: impact of attitudes and perceptions on CAV adoption*

425 The identified four latent variables are estimated based on observed explanatory variables and 426 indicator variables with a structural relationship with socioeconomic and social influence 427 variables. However, only for latent variable CP, in addition to socioeconomic and social influence 428 variables, alternative attribute variables are also included in the structural relationship because of 429 their similarity in capturing purchasing decisions. Model estimation results for the SEM 430 framework for structural and measurement equation models are presented in Table 7 and Table 8, 431 respectively. The model (presented in Table 7 and Table 8) resulted in Adjusted McFadden's ratio 432 value of 0.167.

433 The estimated structural equation part of SEM (Table 7) confirms the relationship or effect of socioeconomic, social influence, and alternative attribute variables on perceptions about the social 434 435 values (SI), CAV benefits, CAV barriers, and CAV purchasing characteristics (see eq (2)). We 436 obtained significant relationships for all the latent variables except for CBe. For CBe, only 437 household income of more than \$110,000 was significant at p-value <0.10. Compared to women, 438 men are more concerned about their social values and less concerned about CAV barriers and 439 CAV purchasing characteristics, if they are buying a CAV. Individuals aged more than 54 years 440 are uninterested in their social values and CAV purchase characteristics. Individuals with ethnicity 441 as white are concerned about CAV purchase characteristics; African American individuals are 442 concerned about CAV barriers when compared to other ethnicities. Also, individuals belonging to 443 ethnicities other than white and black, are more concerned about their social values while

purchasing a CAV but not concerned about CAV purchasing characteristics. As compared to
faculties, staff employees are more concerned about barriers associated with CAV.

Adults with an annual remuneration of more than **\$65,000** are negatively associated with the CAV purchase characteristics, whereas adults with annual income less than \$35,000 are more concerned about the social values. This inverse relationship with social values can be attributed to respondents belonging to an educational institute. Hence, low income might represent staff employees and faculties, and researchers are generally unconcerned about their social image in an institutional environment. Hence, individuals with low personal income representing staff were positively related to social image.





Fig. 3. Integrated choice and latent model: estimation framework

456 Households with a higher number of members are positively associated with the CAV's barriers 457 and impact on social values but unconcerned about the purchasing characteristics. As expected, 458 households with high annual income are not concerned about CAV purchasing characteristics. 459 Individuals **frequently working from home** are not concerned about the impact of CAVs on their 460 social status and CAV's potential benefits, probably as they do not travel to work every day; hence, 461 they are uninterested in driverless capabilities and social values impact of CAVs. Adults with a 462 flexible working schedule are more concerned about the CAV's purchasing characteristics. It can 463 be attributed to their interest in traveling in a CAV during any time of day to attend meetings or 464 workplace and hence are concerned about CAV purchase. As expected, physically challenged 465 adults are concerned about social image and CAV purchasing characteristics because they will rely 466 on CAVs to complete their traveling activities and will undergo a change in a social image with 467 self-dependent mobility.

468 Adults owning a **smartphone or tech-savvy** lifestyle are unconcerned about any of the latent 469 attitudes, which can be attributed to their awareness about the AV technology. Also, the individuals 470 who purchased a car in the last ten years, buy cars frequently, willing to pay less for buying a 471 standard car, and more for CAV maintenance and frequently communicate with social ties are 472 unconcerned about the price, quality or environmental friendliness of CAVs. In terms of the impact 473 of social networks on latent constructs, adults with a greater number of social contacts or ties are 474 concerned about all the latent attitudes. This can be attributed to the transferred information about 475 CAVs in their social network.

The estimated measurement equation part of SEM relates unobserved latent variables to the underlying indicator variables through an ordinal probit kernel through coefficient matrix D (see eq (3)) measured through eq. (4). All the coefficients are significant at the 0.05 level except for

479 CBe and reflect intuitive signs (Table 8). During estimation, for each latent variable, the intercept 480 and coefficient of one indicator variable are kept as the base (zero) so that the other indicators can 481 be interpreted with respect to the base indicator. Among three indicators of latent variable SSI the 482 Ind04 is kept as the base indicator for indicators Ind02 and Ind03. Consequently, in CBa, Ind11 is 483 kept as the base indicator for all other five indicators (Ind06, Ind07, Ind08, Ind09, and Ind10). For 484 CBe, Ind16 is kept as the base for the Ind15. Finally, for CP, Ind23 is kept as the base indicator 485 for two indicators Ind21 and Ind23. As per the base indicator in SI, the interpretation for the other 486 indicators will be: if adults are concerned about their social values after buying a CAV, as 487 compared to improve in status, they are more interested about the inputs from their work and non-488 work social networks which is not surprising as social values depend on the perceived social 489 feedbacks.

490 If individuals are concerned about barriers associated with CAVs then as compared to giving 491 up driving control to AV technology, they are positively associated with all other barriers like 492 system failures - due to poor internet, virus attacks and system breakdown -, less maneuverability 493 of CAVs as compared to regular car and need to take control from AV technology when required. 494 The positive relationship of safety concerns with its indicators is in line with Nazari et al. (2018). 495 This is not surprising as CAVs are not available in the market yet, and these are the anticipated 496 potential barriers. There is no significant relationship between an adult's concern for the benefits 497 of CAVs and its indicators representing benefits. As expected, if an individual is concerned about 498 CAV purchasing characteristics, as compared to the environmental friendliness of CAVs, the 499 individual is more interested in the price and quality of CAVs.

### **Table 7**

# 501 Estimation results of SEM/ latent variable model: structural equation (N=1,714)

			Coefficient (p-value) <sup>Significance</sup>					
	Explanatory variables	Social Image	CAV Barriers	CAV Benefits	CAV Purchase			
Intercept		-1.55(0.502)	-0.644(0.125)	-0.092(0.999)	1.19(0.875)			
	So	cioeconomic variables						
	Less than 40							
Age	40 to 54							
	more than 54	-0.545(0.01)**			-3.59(0.0)***			
Gender ( $1 = male; 0 = female$	) )	-0.545(0.009)**	-0.745(0.0)***	-7.1(0.436)	-3.29(0.0)***			
	White			-3.55(0.445)	0.958(0.043)*			
Race	Black or African American		0.443(0.0)***					
	Others	1.46(0.0)***			-1.09(0.297)			
Employee category (1= staff;	0 = faculty)		0.514(0.0)***	-5.26(0.388)				
	less than \$35,000	1.57(0.0)***						
Approximate annual income	\$35,000-\$65,000							
	more than \$65,000				-2.73(0.0)***			
Frequency of working from	Frequent (once a week to daily)	-1.34(0.0)***		-4.37(0.335)				
home	Sometimes (Once in a month or year)							

	Never			-3.83(0.414)		
Flexibility in work schedule $(1 = yes, 0 = no)$				-1.26(0.531)	2.78(0.0)***	
Any kind of disability which	undermines driving $(1 = yes, 0 = no)$	2.46(0.0)***		2.63(0.467)	4.71(0.0)***	
Number of household membe	rs	1.45(0.0)***	0.311(0.031)**		-1.58(0.076)#	
A	less than \$65,000				-5.19(0.0)***	
Approximate annual	\$65,000-\$110,000		0.429(0.0)***			
household income	more than \$110,000			-1.71(0.066)#	-2.55(0.0)***	
Smartphone ownership $(1 = yes, 0 = no)$		-1.16(0.0)***	-0.246(0.191)	-7.27(0.456)		
Listens to radio $(1 = yes, 0 = no)$					-2.77(0.022)*	
Watches TV $(1 = yes, 0 = no)$					-2.74(0.024)*	
Alternative attribute variables						
Number of owned cars (household)						
New cars purchased over the last 10 years					-3.77(0.005)**	
Used cars purchased over the	last 10 years				2.78(0.006)**	
	Frequently (once every 1 to 5 years)				-1.17(0.029)*	
Frequency of purchasing a	Moderate (once every 10 years)					
car (household)	Infrequent (once every 15 to 20 years)				3.66(0.0)***	
Any plans to buy or sell a new	v car in the next 3 years $(1 = yes, 0 = no)$				1.68(0.002)**	
	less than \$15,000				-0.319(0.518)	

Willingness to pay towards	\$15,000-\$30,000				
buying a regular car	more than \$30,000				
Willingness to pay more	Nothing or \$0				
towards maintaining a CAV	\$0-\$300				
than a regular car (annually)	more than \$300				-2.82(0.0)***
	Social influence	e variables			
Number of close social ties es	tablished at work	3.38(0.0)***	0.641(0.002)**	6.51(0.477)	6.96(0.0)***
Frequency of	Frequent (2-3 times a week to daily)				-2.48(0.0)***
communication with social	Sometimes (every couple of weeks to a month)				
ties developed at work	Infrequent (once per month to every few months)			-3.19(0.226)	
Goodness of fit measures:					
	Init log-likelihood:		-4084	0.44	
	-33916.19				
	13848.5				
	0.17				
	0.167				
	68078.38				
		68748	8.31		

Significance levels: -- not significant, #0.10, \*0.05, \*\*0.01, \*\*\*0.001

# **Table 8**

# 503 Estimation results of the latent variable model: measurement equation (N=1,714)

		Dess indicator veriable		Coefficient (p	-value) <sup>Significance</sup>	
indicator variables		base indicator variable	Social Image	CAV Barriers	CAV Benefits	CAV Purchase
	Intercept		0.334(0.27)			
indu2: workSocialNetimp	Coefficient	Ind04: StatusImprove	0.131(0.0)***			
In d02. Non Work Coois Mathem	Intercept	indo4. Statusinipiove	0.36(0.198)			
Indus: Non workSocialNetimp	Coefficient		0.121(0.0)***			
In 10C De enlaternet	Intercept			1.02(0.001)***		
Induo: Poorinternet	Coefficient			0.497(0.0)***		
Ind07: TakeOver	Intercept			1.06(0.0)***		
indo/. Takeover	Coefficient			0.423(0.0)***		
IndOS. Virus Attack	Intercept	Ind11: FullControl		1.34(0.0)***		
muoo. VirusAttaek	Coefficient	murr. Function		0.489(0.0)***		
Ind00: SystemEailura	Intercept			1.24(0.0)***		
md09. SystemFanure	Coefficient			0.439(0.0)***		
Ind10: LessAgility	Intercept			0.773(0.0)***		
	Coefficient			0.342(0.0)***		

Ind15: Green	Intercept Coefficient	Ind16: MobForDisabled	
Ind 21. CorDrice	Intercept		2.69(0.009)**
Ind21: CarPrice	Coefficient		0.13(0.0)***
Ind22: CarQuality	Intercept	Ind23: Environment	3.25(0.005)**
	Coefficient		0.151(0.0)***

Significance levels: -- not significant, #0.10, \*0.05, \*\*0.01, \*\*\*0.001

goodness of fit: same as SEM structural equation in Table 7

505 

#### 511 4.3 Estimated ordered logit model for levels of likelihood to adopt a CAV

We estimated the effect of explanatory variables over the likelihood of adopting a CAV with an ordinal logit framework with latent variables. In ICLV, the estimated latent variables from indicator variables along with the socioeconomic, alternative attribute, and social influence variables, contribute in predicting choice outcome, i.e., three levels of adoption likelihood incorporated into utility equation, used as explanatory variables along with the socioeconomic, alternative attribute, and social influence variables, (See eq. (1)) and then utility is measured through an ordinal logit framework (Eq. (5)).

519 We also removed the latent variables from the estimated ICLV model to formulate a reduced 520 choice model (ordinal logit without latent variables) to compare the goodness of fit of both the 521 models and check whether ICLV provides additional and better prediction of choice behavior. 522 Also, in order to keep models comparable, we included all the variables of ICLV (present in 523 structural equations of both SEM and DCM) in the reduced choice model. We also kept the 524 insignificant variables in reduced ordinal logit to keep the difference between models as significant 525 (Vij and Walker, 2016). We used equation 9 to calculate goodness of fit measures for ICLV, which 526 are different from measures provided in Table 7 as the former does not include indicator variables 527 (discussed in subsection 3.3). Table 9 delineates the AIC and BIC values for two models, and 528 lower BIC values in the ICLV model vindicates its superiority in predicting the choice behavior 529 over the reduced ordinal logit model.

530

531

532

#### 534 **Table 9**

Fit index	Reduced choice model	ICLV
AIC	12,949.29	7,352.581
BIC	13,129.03	7,505.085

#### 535 Model comparison: Reduced choice model vs. ICLV (N=1,714)

536

537 The model resulted in a cross-validation score of 76% (accuracy), which implies no overfitting 538 on the training dataset. In addition to the accuracy, we also provide the confusion matrix for the 539 ordered logit model with latent variables in Table 10 and Table 11. The model predicted less likely 540 likelihood, most accurately followed by equally likely and more likely.

#### 541 Table 10

542	Confusion	matrix	for	ordered	logit	with	latent	variables	(N=735	)
									<b>\</b>	

Predicted outcome Actual outcome	Less likely	Equally likely	More likely
Less likely	219	61	0
Equally likely	40	258	14
More likely	4	56	83

543

The results for ordinal logit with latent variables for likelihood to adopt a CAV with three levels – less likely, equally likely, and more likely - are enumerated in Table 11. The sign of estimates can be interpreted as positive implies towards the highest level (more likely), and negative sign implies towards the lowest level (less likely).

#### 549 **Table 11**

	Precision	Recall	F1-score	Observations
Likelihood to adopt: less likely	0.83	0.78	0.81	280
Likelihood to adopt: equally likely	0.69	0.83	0.75	312
Likelihood to adopt: more likely	0.86	0.58	0.69	143
	Accuracy		0.76	

#### 550 Classification report for ordered logit with latent variables (N=735)

551 To answer our hypothesis of the effect of social values on the likelihood of adopting a CAV, 552 the coefficient for the latent variable SI is negatively related. Therefore, if adults perceive that 553 buying a CAV will increase their social image, they will be less likely to adopt the CAVs. To the 554 best of our knowledge, we did not find any previous studies on the effect of social interactions on 555 the likelihood to adopt, and our research is novel in this area. However, since CAVs are still in 556 incipient stage and are not available in the market yet, this might be an explanation of less likely 557 to adopt even if adopting would increase their social status (Leicht et al., 2018; Nordhoff et al., 558 2018; Panagiotopoulos and Dimitrakopoulos, 2018). Leicht et al. (2018) found a positive 559 relationship of consumer innovativeness on social influence and purchase intention, and 560 Panagiotopoulos and Dimitrakopoulos (2018) also found a positive relationship between social 561 influence and intention to use. However, purchase intention is incomparable with WTP to adopt. 562 Similarly, findings of Nordhoff et al. (2018) concluded social influence as the deciding factor in 563 adopting CAVs.

Also, the likelihood to adopt is related negatively with latent variables CBa and CP, whereas there is an insignificant relationship with CAV Benefits. An interaction between **disability status** and latent variable **CBa** indicates that even if an individual is disabled and concerned about the 567 barriers associated with CAV, the individual will still be less likely to adopt a CAV, which makes 568 sense because of the incipient stage and barriers outweighing benefits of CAVs. Individuals' 569 resistance to adopt CAVs because of the associated problems or barriers conform to the previous 570 studies (Lavieri et al., 2017; Nazari et al., 2018). Since CAVs are not available in the market yet, 571 hence CAV purchasing characteristics are related negatively with the likelihood of their adoption. 572 There is no significant effect of age and gender on adoption likelihood. However, individuals 573 belonging to white ethnicity are less likely to adopt a CAV. As expected, households with high 574 incomes are more likely to adopt CAVs, which is consistent with previous literature (Bansal et al., 575 2016; Bansal and Kockelman, 2018; Kyriakidis et al., 2015; Liu et al., 2019a; Shabanpour et al., 576 2018). Owning a smartphone has no impact on the likelihood of adopting CAVs. Also, as expected, 577 if individuals purchased a new car in the last ten years, they will be less likely to buy a CAV as it 578 will be too early for them to spend more money on buying another car.

579 Similarly, the frequency of purchasing a car is positively related to the likelihood to adopt a 580 CAV as the less frequency implies buying a car equipped with the latest technology, which comes 581 at high costs. In contrast, the high frequency may imply spending more amount of money once the 582 existing car completes its lifetime (15 to 20 years). However, if an individual is interested in buying 583 or selling a car in the next three years, he will be willing to pay less for a CAV, which can be due 584 to the incipient stage of autonomous technology. WTP for the **annual maintenance** of a CAV has 585 no significant impact on their adoption likelihood. If an individual is willing to pay a higher 586 amount to buy a regular car, then the individual will be more likely to adopt a CAV, which can be 587 attributed to added features in higher priced regular cars, which is analogous to vehicle automation 588 features in CAVs. This finding is in line with Berliner et al. (2019). Social influence variables had 589 no direct influence over choice outcomes and were removed from the model.

### **590 Table 12**

591 Estimated ordered logit model (with latent variables) for capturing likelihood to adopt CAVs 592 (N=1,714)

	Coefficient (p-value) <sup>Significance</sup>		
Intercept		-2.78(0.658)	
	Socioeconomic variables		
	Less than 40		
Age	40 to 54		
	more than 54	-0.032(0.819)	
Gender (1 = male; 0 = female	) ?)		
	White	-2.62(0.0)***	
Race	Black or African American		
	Others		
Employee category (1= staff;	0 = faculty)	0.436(0.379)	
	less than \$35,000		
Approximate annual income	\$35,000-\$65,000		
	more than \$65,000		
	Frequent (daily to once a week)		
Frequency of working from	Sometimes (Once in a month or year)		
home	Never		
Flexibility in work schedule (	1 = yes, 0 = no)		
Any kind of disability which	undermines driving $(1 = yes, 0 = no)$	-0.666(0.716)	
Number of household membe	prs		
	less than \$65,000		
Approximate annual	\$65,000-\$110,000		
nousenold income	more than \$110,000	1.05(0.0)***	
Smartphone ownership $(1 = y)$	0.245(0.803)		

Listens to radio	(1 :	= yes,	0 =	no)
------------------	------	--------	-----	-----

Watches TV (1	= yes, $0 =$ no)
---------------	------------------

Alternative attribute variables			
Number of owned cars (house	ehold)		
New cars purchased over the last 10 years		-0.535(0.032)*	
Used cars purchased over the	last 10 years		
Frequency of purchasing a car (household)	Frequently (once every 1 to 5 years)	0.42(0.012)*	
	Moderate (once every 10 years)		
	Infrequent (once every 15 to 20 years)	0.78(0.0)***	
Any plans to buy or sell a new car in next 3 years $(1 = yes, 0 = no)$		-0.608(0.0)***	
Willingness to pay towards buying a regular car	less than \$15,000	0.537(0.001)***	
	\$15,000-\$30,000		
	more than \$30,000	0.632(0.001)***	
Willingness to pay more	Nothing or \$0	-2.22(0.291)	
towards maintaining a CAV	\$0-\$300	0.443(0.832)	
than a regular car (annually)	more than \$300	2.0(0.344)	
Latent Variables			

Social Image (SI)	-0.108(0.001)***
CAV Barrier (CBa)	-0.197(0.012)*
CAV Barrier * disabled	-2.81(0.0)***
CAV Benefits (CBe)	-0.187(0.138)
CAV Purchase (CP)	-0.057(0.006)**
Threshold 1	-0.056(0.993)
Threshold 2	3.854(0.0)***

Significance levels: -- not significant, #0.10, \*0.05, \*\*0.01, \*\*\*0.001

goodness of fit: same as SEM structural equation in Table 7

--

--

#### 593 4.4 Policy implications

594 This study highlights certain policy and practical implications. Such implications might 595 provide useful insights about the role of consumer's attitudes, psychosocial factors, perceptions, 596 and demographics towards CAV adoption in the form of their concern towards social values, 597 benefits, barriers, and purchasing characteristics of CAVs to automaker industry and 598 policymakers. We choose to describe such implications after scrutinizing the estimation results 599 (Table 7 and Table 12) and marginal effects (Table 13) of ICLV model. The results of the latent 600 variable model (Table 7) imply positive concern towards the different benefits and barriers 601 associated with CAVs, which in turn affects consumers' trust in AV technology. Increased social 602 influence, in the form of an increased number of contacts/ties, tends to make the individual more 603 concerned about the quality, price, and environmental friendliness of CAVs. As far as barriers 604 associated with CAVs are concerned, the positive impact of increased social ties can contribute to 605 resolving them through proper information ways to overcome the barriers. For instance, if any 606 individual is concerned about cybersecurity and privacy, advertising proper information regarding 607 the anticipated precautions will help in resolving such concerns, which in turn will contribute to 608 increased market penetration of CAVs. Technology savviness (smartphone ownership) is 609 negatively related to attitudinal concerns. Hence, if a person owns a smartphone, then they do not 610 care much about barriers associated with CAVs, which in turn will affect the likelihood to adopt 611 CAVs.

612 Second, the results of ordinal logit model with latent variables (Table 12) imply that CAVs 613 will have a positive impact on an adult's social network and are equivalent to a luxury car, however, 614 less knowledge or exposure about AV technology makes the adult less likely to buy a CAV. AV 615 technology and social interaction make it more evident for the consumer about the anticipated barriers outweighing benefits. Also, even if an individual is disabled and concerned about the problems of CAVs, the individual will still be less likely to adopt, which again highlights the importance of the adverse problems or barriers of CAVs, and these insights will help policymakers in overcoming all the barriers.

620 Third, we also choose to scrutinize the effect of change in different exogenous variables on the 621 choice probability of adoption likelihood using marginal effects (Table 13). One unit increase in 622 latent variable or perception about the impact on social values could increase and decrease both 623 less and more likely levels by 3%. However, one unit increase in latent variable Social Image will 624 decrease the equally likely likelihood by 25%. One unit increase in attitude towards CAV barriers 625 could decrease an individual's likelihood of equally likely by 9%. One unit increase in perceptions 626 towards the purchase characteristics associated with CAVs increases an individual's intention to 627 equally and more likely to adopt a CAV by 5% and 43%, respectively. Hence, individuals who are 628 equally likely to adopt a CAV has a high potential of shifting to less/more likely depending on the 629 impact of CAVs on their concerns towards the social image, anticipated barriers and purchasing 630 characteristics.

Hence the impact of social interaction, anticipated barriers, and purchase characteristics on the likelihood to adopt a CAV implies the dire need for future efforts in educating and informing potential consumers about the ways to solve anticipated problems can pave the way for increased CAV adoption. Individuals' susceptibility towards purchase characteristics of CAVs implies the need to advertise or disseminate information about the attractive features of CAVs to the general public. Hence, automakers and policymakers will need to be wary about these characteristics of CAVs to increase their market penetration. Therefore, policies targeting awareness and educating 638 the consumers with the technological benefits of CAVs will be beneficial for increased CAV

- 639 adoption in its early stages.
- 640 **Table 13**
- 641 Estimated marginal effects for ordered logit model (with latent variables) for measuring
- 642 individual's likelihood to adopt a CAV (N=1,714)

Explanatory variables	Willingness to pay		
	Less	Moderate	More

#### Socioeconomic variables

	White	0.0490	-0.2983	-0.4978
Race	Black or African American			
	Others			
Approximate annual household income	less than \$65,000			
	\$65,000-\$110,000			
	more than \$110,000	-0.0054	0.0269	0.0896
Alternative attribute variables				
New cars purchased over the last 10 years		0.0129	-0.0810	-0.1161
Frequency of purchasing a car (household)	Frequently (once every 1 to 5 years)	0.0022	-0.0123	-0.0297
	Moderate (once every 10 years)			
	Infrequent (once every 15 to 20 years)	-0.0099	0.0169	0.3383
Any plans to buy or sell a new car in the next 3 years $(1 = yes, 0 = no)$		0.0149	-0.0759	-0.2330
Willingness to pay towards buying a regular car	less than \$15,000	0.0001	-0.0007	-0.0012
	\$15,000-\$30,000			
	more than \$30,000	-0.0009	0.0043	0.0166

Latent Variables			
Social Image	0.0319	-0.2478	-0.0313
CAV Barrier	0.0120	-0.0942	-0.0043
CAV Purchase	-0.0174	0.0593	0.4312

\* Bold estimates indicate maximum and minimum

#### 643 **5.** Conclusions

644 In this paper, we propose to contribute to identifying the relationship of individuals' socioeconomic 645 characteristics, vehicle ownership, attitudes, and perceptions towards CAVs with the anticipated 646 likelihood to adopt CAVs. We are contributing in terms of studying the effect of an individuals' 647 social network or values on their behavior towards adopting CAVs. To achieve this, we utilized 648 an integrated choice and latent variable (ICLV) modeling framework based on an institutional 649 dataset. First, we performed an exploratory factor analysis to identify the psychosocial and 650 attitudinal constructs. Then we estimated the ICLV modeling framework to estimate the impact of 651 identified attitudinal concern on likelihood towards CAV adoption. We also modeled a reduced 652 choice model (ordinal logit without latent variables) to compare the performance of ICLV.

653 Results revealed four attitudinal variables reflecting the importance of social values and CAV 654 characteristics like benefits, barriers, and purchase attributes while purchasing a CAV. ICLV 655 framework outperformed ordinal logit without latent variables in terms of increased likelihood and 656 behavioral interpretation of attitude and perceptions. Results revealed a positive impact of adopting 657 CAVs on the social values of an individual. Households with high annual income, willing to pay 658 more to buy a regular car and frequent car buyers are more likely to adopt CAVs. Individuals are 659 less likely to adopt a CAV if they are concerned about associated barriers and purchasing 660 characteristics of CAVs. Besides, technology savviness was related negatively with perception 661 towards the social image on adopting a CAV.

662 This study includes limitations in terms of the sampling frame (institutional audience as target 663 population), cross-sectional stated preference survey including only personally owned CAVs as 664 mode choice, and synthetic population. The dataset used in this study did not consider any 665 questions about shared autonomous vehicles (SAVs); study scope is limited to personally owned 666 CAVs and educational institute synthetic population. Future research directions with a survey 667 covering respondents with the general population with owned and shared CAVs will further bolster 668 policy implications. The target population in this study is an institutional audience, and since such 669 an audience is more exposed to technological innovations at an early stage and often interacts with 670 their colleague researchers involved in such technological innovations, their preferences towards 671 CAVs will provide the automakers key takeaways for pricing and advertising such vehicles. 672 Hence, the findings of this study will provide key insights to the policymakers, automakers, and 673 planners to identify the factors affecting the price of CAVs, including the peer social network 674 interaction, and frame or implement policies/plans accordingly. The study results should be 675 considered with some caveats as the findings are based on a population with certain employment 676 types in a university context and not from a general population.

#### 677 Acknowledgments

This research is partly funded by the Tennessee Department of Transportation and Freight Mobility Research Institute, a US Department of Transportation University Transportation Research Center. The opinions provided in the paper are those of the authors and not of the aforementioned agencies.

#### 682 References

683 Acheampong, R.A., Cugurullo, F., 2019. Capturing the behavioural determinants behind the

- adoption of autonomous vehicles: Conceptual frameworks and measurement models to
  predict public transport, sharing and ownership trends of self-driving cars. Transp. Res. part
  F traffic Psychol. Behav. 62, 349–375.
- Asgari, H., Jin, X., 2019. Incorporating Attitudinal Factors to Examine Adoption of and
  Willingness to Pay for Autonomous Vehicles. Transp. Res. Rec.
  https://doi.org/10.1177/0361198119839987
- Atasoy, B., Glerum, A., Bierlaire, M., 2013. Attitudes towards mode choice in Switzerland. Disp
  49, 101–117. https://doi.org/10.1080/02513625.2013.827518
- Auld, J., Mohammadian, A., 2010. Efficient Methodology for Generating Synthetic Populations
  with Multiple Control Levels. Transp. Res. Rec. 2175, 138–147.
  https://doi.org/10.3141/2175-16
- Bansal, P., Kockelman, K.M., 2018. Are we ready to embrace connected and self-driving vehicles?
  A case study of Texans. Transportation (Amst). 45, 641–675. https://doi.org/10.1007/s11116016-9745-z
- Bansal, P., Kockelman, K.M., 2017. Forecasting Americans' long-term adoption of connected and
- autonomous vehicle technologies. Transp. Res. Part A Policy Pract. 95, 49–63.
  https://doi.org/10.1016/j.tra.2016.10.013
- 701 Bansal, P., Kockelman, K.M., Singh, A., 2016. Assessing public opinions of and interest in new
- vehicle technologies: An Austin perspective. Transp. Res. Part C Emerg. Technol. 67, 1–14.
  https://doi.org/10.1016/j.trc.2016.01.019
- Bartlett, M.S., 1950. Tests of significance in factor analysis. Br. J. Stat. Psychol. 3, 77–85.
- 705 Becker, F., Axhausen, K.W., 2017. Literature review on surveys investigating the acceptance of
- automated vehicles. Transportation (Amst). 44, 1293–1306. https://doi.org/10.1007/s11116-

707 017-9808-9

- 708 Ben-Akiva, M., Mcfadden, D., Train, K., Walker, J., Bhat, C., Bierlaire, M., Bolduc, D., Boersch-709 Supan, A., Brownstone, D., Bunch, D.S., Daly, A., De Palma, A., Gopinath, D., Karlstrom,
- 710 A., Munizaga, M.A., 2002. Hybrid Choice Models: Progress and Challenges. Mark. Lett. 13,
- 711 163–175. https://doi.org/10.1023/A:1020254301302
- 712 Bentler, P.M., 1990. Comparative fit indexes in structural models. Psychol. Bull. 107, 238.
- 713 Berliner, R.M., Hardman, S., Tal, G., 2019. Uncovering early adopter's perceptions and purchase
- 714 intentions of automated vehicles: Insights from early adopters of electric vehicles in
- 715 California. Transp. Res. Part F Traffic Psychol. Behav. 716
- https://doi.org/10.1016/j.trf.2018.11.010
- 717 Bierlaire, M., 2018. Estimating choice models with latent variables with PandasBiogeme.
- 718 Bouscasse, H., 2018. Integrated choice and latent variable models: A literature review on mode 719 choice. Work. Pap. GAEL.
- 720 Casley, S.V., Jardim, A., Quartulli, A.M., 2013. A Study of Public Acceptance of Autonomous 721 Cars. Bachelor Sci. thesis. Worcester Polytechnic Institute, Worcester, MA, USA. 722 https://doi.org/10.1016/j.ympev.2009.08.027
- 723 Cerny, B.A., Kaiser, H.F., 1977. A study of a measure of sampling adequacy for factor-analytic 724 correlation matrices. Multivariate Behav. Res. 12, 43–47.
- 725 Chen, F., Curran, P.J., Bollen, K.A., Kirby, J., Paxton, P., 2008. An empirical evaluation of the 726 use of fixed cutoff points in RMSEA test statistic in structural equation models. Sociol. 727 Methods Res. 36, 462–494.
- 728 Cheung, C.M.K., Xiao, B.S., Liu, I.L.B., 2014. Do actions speak louder than voices? The signaling
- 729 role of social information cues in influencing consumer purchase decisions. Decis. Support

- 730 Syst. 65, 50–58. https://doi.org/https://doi.org/10.1016/j.dss.2014.05.002
- Cunningham, M.L., Regan, M.A., Ledger, S.A., Bennett, J.M., 2019. To buy or not to buy?
  Predicting willingness to pay for automated vehicles based on public opinion. Transp. Res.
  Part F Traffic Psychol. Behav. 65, 418–438.
  https://doi.org/https://doi.org/10.1016/j.trf.2019.08.012
- Daziano, R.A., Bolduc, D., 2013. Incorporating pro-environmental preferences towards green
  automobile technologies through a Bayesian hybrid choice model. Transp. A Transp. Sci. 9,
  74–106.
- 738 Daziano, R.A., Sarrias, M., Leard, B., 2017. Are consumers willing to pay to let cars drive for
- them? Analyzing response to autonomous vehicles. Transp. Res. Part C Emerg. Technol. 78,
  150–164. https://doi.org/10.1016/j.trc.2017.03.003
- El Zarwi, F., Vij, A., Walker, J.L., 2017. A discrete choice framework for modeling and forecasting
  the adoption and diffusion of new transportation services. Transp. Res. Part C Emerg.
  Technol. 79, 207–223. https://doi.org/10.1016/j.trc.2017.03.004
- Fabrigar, L.R., Wegener, D.T., MacCallum, R.C., Strahan, E.J., 1999. Evaluating the use of
  exploratory factor analysis in psychological research. Psychol. Methods 4, 272.
- 746 Fagnant, D.J., Kockelman, K., 2015. Preparing a nation for autonomous vehicles: Opportunities,
- barriers and policy recommendations. Transp. Res. Part A Policy Pract. 77, 167–181.
- 748 https://doi.org/10.1016/j.tra.2015.04.003
- 749 Gkartzonikas, C., Gkritza, K., Drive, S.M., Lafayette, W., States, U., 2019. What have we learned?
- A review of stated preference and choice studies on autonomous vehicles 98, 323–337.
- 751 https://doi.org/10.1016/j.trc.2018.12.003
- Guo, J.Y., Bhat, C.R., 2007. Population Synthesis for Microsimulating Travel Behavior. Transp.

- 753 Res. Rec. 2014, 92–101. https://doi.org/10.3141/2014-12
- Gurney, J.K., 2013. Sue My Car Not Me: Products Liability and Accidents Involving Autonomous
  Vehicles, Journal of Law, Technology and Policy.
- 756 Haboucha, C.J., Ishaq, R., Shiftan, Y., 2017. User preferences regarding autonomous vehicles.
- 757 Transp. Res. Part C Emerg. Technol. 78, 37–49. https://doi.org/10.1016/j.trc.2017.01.010
- Hinkle, D.E., Wiersma, W., Jurs, S.G., 2003. Applied statistics for the behavioral sciences.
  Houghton Mifflin College Division.
- Howard, D., Dai, D., 2014. Public Perceptions of Self-driving Cars: The Case of Berkeley,
  California. Transp. Res. Board 93rd Annu. Meet. 14, 21.
- Hu, L., Bentler, P.M., 1999. Cutoff criteria for fit indexes in covariance structure analysis:
  Conventional criteria versus new alternatives. Struct. Equ. Model. A Multidiscip. J. 6, 1–55.
  https://doi.org/10.1080/10705519909540118
- Jiang, Y., Zhang, J., Wang, Y., Wang, W., 2019. Capturing ownership behavior of autonomous
- vehicles in Japan based on a stated preference survey and a mixed logit model with repeated
- 767
   choices.
   Int.
   J.
   Sustain.
   Transp.
   13,
   788–801.

   768
   https://doi.org/10.1080/15568318.2018.1517841
- Joewono, T.B., 2009. Exploring the willingness and ability to pay for paratransit in Bandung,
  Indonesia. J. public Transp. 12, 5.
- Kaur, K., Rampersad, G., 2018. Trust in driverless cars: Investigating key factors influencing the
  adoption of driverless cars. J. Eng. Technol. Manag. 48, 87–96.
  https://doi.org/https://doi.org/10.1016/j.jengtecman.2018.04.006
- Kim, K.S., Vandebona, U., 1999. User Requirements and Willingness To Pay for Traffic
  Information Systems: Case Study of Sydney, Australia. Transp. Res. Rec. 1694, 42–47.

776 https://doi.org/10.3141/1694-06

777 Kline, R.B., 2015. Principles and practice of structural equation modeling. Guilford publications.

- 778 Krueger, R., Rashidi, T.H., Rose, J.M., 2016a. Preferences for shared autonomous vehicles.
- 779 Transp. Res. Part C Emerg. Technol. 69, 343–355. https://doi.org/10.1016/j.trc.2016.06.015
- 780 Krueger, R., Rashidi, T.H., Rose, J.M., 2016b. Adoption of Shared Autonomous Vehicles-A
- Hybrid Choice Modeling Approach Based on a Stated-Choice Survey. Present. 95th Annu.
  Meet. Transp. Res. Board, Washington, D.C 20 pages.
- 783 Kyriakidis, M., Happee, R., De Winter, J.C.F., 2015. Public opinion on automated driving: Results
- of an international questionnaire among 5000 respondents. Transp. Res. Part F Traffic
  Psychol. Behav. 32, 127–140. https://doi.org/10.1016/j.trf.2015.04.014
- LaFrance, J.T., 1993. Weak separability in applied welfare analysis. Am. J. Agric. Econ. 75, 770–
  787 775.
- 788 Lavieri, P.S., Garikapati, V.M., Bhat, C.R., Pendyala, R.M., Astroza, S., Dias, F.F., 2017. 789 Modeling Individual Preferences for Ownership and Sharing of Autonomous Vehicle 790 Technologies. Rec. J. Transp. Board 1 - 10.Transp. Res. Res. 2665, 791 https://doi.org/10.3141/2665-01
- Lee, D., Mulrow, J., Haboucha, C.J., Derrible, S., Shiftan, Y., 2019. Attitudes on autonomous
  vehicle adoption using interpretable gradient boosting machine. Transp. Res. Rec. 2673, 865–
  878.
- Lee, J., Lee, D., Park, Y., Lee, S., Ha, T., 2019. Autonomous vehicles can be shared, but a feeling
  of ownership is important: Examination of the influential factors for intention to use
  autonomous vehicles. Transp. Res. Part C Emerg. Technol. 107, 411–422.
- 798 Leicht, T., Chtourou, A., Ben Youssef, K., 2018. Consumer innovativeness and intentioned

- autonomous car adoption. J. High Technol. Manag. Res. 29, 1–11.
  https://doi.org/https://doi.org/10.1016/j.hitech.2018.04.001
- 801 Lera-López, F., Sánchez, M., Faulin, J., Cacciolatti, L., 2014. Rural environment stakeholders and
- 802 policy making: Willingness to pay to reduce road transportation pollution impact in the
- Western Pyrenees. Transp. Res. Part D Transp. Environ. 32, 129–142.
  https://doi.org/https://doi.org/10.1016/j.trd.2014.07.003
- Liljamo, T., Liimatainen, H., Pöllänen, M., 2018. Attitudes and concerns on automated vehicles.
  Transp. Res. part F traffic Psychol. Behav. 59, 24–44.
- Liu, P., Guo, Q., Ren, F., Wang, L., Xu, Z., 2019a. Willingness to pay for self-driving vehicles:
  Influences of demographic and psychological factors. Transp. Res. Part C Emerg. Technol.
  100, 306–317. https://doi.org/10.1016/j.trc.2019.01.022
- 810 Liu, P., Yang, R., Xu, Z., 2019b. Public Acceptance of Fully Automated Driving: Effects of Social
- 811 Trust and Risk/Benefit Perceptions. Risk Anal. 39, 326–341.
  812 https://doi.org/10.1111/risa.13143
- Malokin, A., Circella, G., Mokhtarian, P.L., 2015. How Do Activities Conducted while
  Commuting Influence Mode Choice? Testing Public Transportation Advantage and
  Autonomous Vehicle Scenarios. TRB 94th Annu. Meet. 6, 1–17.
- Manfreda, A., Ljubi, K., Groznik, A., 2019. Autonomous vehicles in the smart city era: An
  empirical study of adoption factors important for millennials. Int. J. Inf. Manage. 102050.
- 818 McFadden, D., 1986. The Choice Theory Approach to Market Research. Mark. Sci. 5, 275–297.
- 819 Menon, N., Pinjari, A.R., Zhang, Y., Zou, L., 2015. Consumer Perception and Intended Adoption
- 820 of Autonomous Vehicle Technology Findings from a University Population Survey 6, 1–
- 821 23.

- 822 Milakis, D., van Arem, B., van Wee, B., 2017. Policy and society related implications of automated
- driving: A review of literature and directions for future research. J. Intell. Transp. Syst. 21,
- 824 324–348. https://doi.org/10.1080/15472450.2017.1291351
- 825 Nair, G.S., Astroza, S., Bhat, C.R., Khoeini, S., Pendyala, R.M., 2018. An application of a rank
- 826 ordered probit modeling approach to understanding level of interest in autonomous vehicles.
- 827 Transportation (Amst). 45, 1623–1637. https://doi.org/10.1007/s11116-018-9945-9
- 828 Nazari, F., Noruzoliaee, M., Kouros, A.(, Mohammadian, ), 2018. Shared versus private mobility:
- 829 Modeling public interest in autonomous vehicles accounting for latent attitudes. Transp. Res.
- 830 Part C 97, 456–477. https://doi.org/10.1016/j.trc.2018.11.005
- 831 NCSL, 2018. Autonomous vehcles: Self driving enacted legislation [WWW Document]. URL
- 832 http://www.ncsl.org/research/transportation/autonomous-vehicles-self-driving-vehicles-
- enacted-legislation.aspx (accessed 11.20.18).
- Nordhoff, S., De Winter, J., Kyriakidis, M., Van Arem, B., Happee, R., 2018. Acceptance of
  driverless vehicles: Results from a large cross-national questionnaire study. J. Adv. Transp.
  2018.
- Panagiotopoulos, I., Dimitrakopoulos, G., 2018. An empirical investigation on consumers'
  intentions towards autonomous driving. Transp. Res. part C Emerg. Technol. 95, 773–784.
- 839 Payre, W., Cestac, J., Delhomme, P., 2014. Intention to use a fully automated car: Attitudes and a
- priori acceptability. Transp. Res. Part F Traffic Psychol. Behav. 27, 252–263.
  https://doi.org/10.1016/j.trf.2014.04.009
- Pettigrew, S., Dana, L.M., Norman, R., 2019. Clusters of potential autonomous vehicles users
  according to propensity to use individual versus shared vehicles. Transp. Policy.
  https://doi.org/10.1016/j.tranpol.2019.01.010

- Pituch, K.A., Stevens, J.P., 2015. Applied multivariate statistics for the social sciences: Analyses
  with SAS and IBM's SPSS. Routledge.
- 847 Raveau, S., Álvarez-Daziano, R., Yáñez, M.F., Bolduc, D., de Dios Ortúzar, J., 2010. Sequential
- and Simultaneous Estimation of Hybrid Discrete Choice Models. Transp. Res. Rec. J. Transp.
- Res. Board 2156, 131–139. https://doi.org/10.3141/2156-15
- 850 Revelle, W., Revelle, M.W., 2015. Package 'psych.' Compr. R Arch. Netw.
- Schoettle, B., Sivak, M., 2014a. A survey of public opinion about connected vehicles in the U.S.,
  the U.K., and Australia. https://doi.org/10.1109/ICCVE.2014.7297637
- 853 Schoettle, B., Sivak, M., 2014b. Public Opinion About Self-Driving Vehicles in China, India,
- Japan, The U.S., The U.K. and Australia. https://doi.org/UMTRI-2014-30
- Shabanpour, R., Golshani, N., Shamshiripour, A., Mohammadian, A. (Kouros), 2018. Eliciting
  preferences for adoption of fully automated vehicles using best-worst analysis. Transp. Res.
- 857 Part C Emerg. Technol. 93, 463–478. https://doi.org/10.1016/j.trc.2018.06.014
- 858 Shabanpour, R., Mousavi, S.N.D., Golshani, N., Auld, J., Mohammadian, A., 2017. Consumer
- 859 preferences of electric and automated vehicles, in: 2017 5th IEEE International Conference
- 860 on Models and Technologies for Intelligent Transportation Systems (MT-ITS). IEEE, pp.
  861 716–720.
- 862 Shin, J., Bhat, C.R., You, D., Garikapati, V.M., Pendyala, R.M., 2015a. Consumer preferences and
- willingness to pay for advanced vehicle technology options and fuel types. Transp. Res. Part
  C Emerg. Technol. 60, 511–524. https://doi.org/10.1016/j.trc.2015.10.003
- Shin, J., Bhat, C.R., You, D., Garikapati, V.M., Pendyala, R.M., 2015b. Consumer preferences
  and willingness to pay for advanced vehicle technology options and fuel types. Transp. Res.
- 867 Part C Emerg. Technol. 60, 511–524.

- 868 https://doi.org/https://doi.org/10.1016/j.trc.2015.10.003
- Simpson, J.R., Mishra, S., 2020. Developing a methodology to predict the adoption rate of
   Connected Autonomous Trucks in transportation organizations using peer effects. Res.
- 871 Transp. Econ. 100866. https://doi.org/https://doi.org/10.1016/j.retrec.2020.100866
- 872 Simpson, J.R., Mishra, S., Talebian, A., Golias, M.M., 2019. An estimation of the future adoption
- 873 rate of autonomous trucks by freight organizations. Res. Transp. Econ. 100737.
  874 https://doi.org/10.1016/j.retrec.2019.100737
- 875 Spurlock, C.A., Sears, J., Wong-Parodi, G., Walker, V., Jin, L., Taylor, M., Duvall, A., Gopal, A.,
- Todd, A., 2019. Describing the users: Understanding adoption of and interest in shared,
- 877 electrified, and automated transportation in the San Francisco Bay Area. Transp. Res. Part D
  878 Transp. Environ. 71, 283–301.
- Talebian, A., Mishra, S., 2018. Predicting the adoption of connected autonomous vehicles: A new
  approach based on the theory of diffusion of innovations. Transp. Res. Part C Emerg.
  Technol. 95, 363–380. https://doi.org/10.1016/j.trc.2018.06.005
- 882 Tussyadiah, I.P., Zach, F.J., Wang, J., 2017. Attitudes toward autonomous on demand mobility
- system: The case of self-driving taxi, in: Information and Communication Technologies in
  Tourism 2017. Springer, pp. 755–766.
- Venkatesh, V., Morris, M.G., Davis, G.B., Davis, F.D., 2003. User Acceptance of Information
  Technology: Toward a Unified View. MIS Q. 27, 425–478. https://doi.org/10.2307/30036540
- 887 Vij, A., Walker, J.L., 2016. How, when and why integrated choice and latent variable models are
- latently useful. Transp. Res. Part B Methodol. 90, 192–217.
  https://doi.org/https://doi.org/10.1016/j.trb.2016.04.021
- 890 Walker, J., 2018. The Self-Driving Car Timeline Predictions from the Top 11 Global

- Automakers [WWW Document]. URL https://www.techemergence.com/self-driving-car timeline-themselves-top-11-automakers/
- Walker, J., 2001. Extended Discrete Choice Models: Integrated Framework, Flexible Error
  Structures, and Latent Variables. PhD thesis, Massachusetts Inst. Technol. 208.
  https://doi.org/http://transp-or.epfl.ch/courses/dca2012/WalkerPhD.pdf
- Wang, Q., Dacko, S., Gad, M., 2008. Factors influencing consumers' evaluation and adoption
  intention of really-new products or services: prior knowledge, innovativeness and timing of
  product evaluation. ACR North Am. Adv.
- Wang, S., Zhao, J., 2019. Risk preference and adoption of autonomous vehicles. Transp. Res. Part
  A Policy Pract. 126, 215–229.
- Wang, X., Yu, C., Wei, Y., 2012. Social Media Peer Communication and Impacts on Purchase
  Intentions: A Consumer Socialization Framework. J. Interact. Mark. 26, 198–208.
  https://doi.org/https://doi.org/10.1016/j.intmar.2011.11.004
- Waymo, 2018. On the Road- Waymo [WWW Document]. URL https://waymo.com/ontheroad/
  (accessed 11.20.18).
- Wolinetz, L.D., Khattak, A.J., Yim, Y., 2001. Why Will Some Individuals Pay for Travel
  Information When It Can Be Free? Analysis of a Bay Area Traveler Survey. Transp. Res.
  Rec. 1759, 9–18. https://doi.org/10.3141/1759-02
- Yáñez, M.F., Raveau, S., Ortúzar, J. de D., 2010. Inclusion of latent variables in mixed logit
  models: modelling and forecasting. Transp. Res. Part A Policy Pract. 44, 744–753.